

The correlation between locomotor performance and hindlimb kinematics during burst locomotion in the Florida scrub lizard, *Sceloporus woodi*

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In Table 2, the heading for columns 7 and 8 should have read 'Combined' rather than 'Stride 3'. The correct version of the table is given below.

Table 2. Results of the hierarchical partitioning analysis

	Stride 1				Stride 3				Combined			
	Final speed		Peak mass-specific power		Final speed		Final speed		Total acceleration		Peak acceleration	
	<i>I</i>	<i>J</i>	<i>I</i>	<i>J</i>	<i>I</i>	<i>J</i>	<i>I</i>	<i>J</i>	<i>I</i>	<i>J</i>	<i>I</i>	<i>J</i>
Min. hip Θ	–	–	0.12	0.11	0.06	0.22	–	–	–	–	–	–
Min. knee Θ	–	–	–	–	0.15	0.28	–	–	0.11	0.17	0.10	0.17
Min. ankle Θ	0.06	–0.06	–	–	0.10	0.30	0.10	–0.05	–	–	–	–
Min. MTP Θ	0.15	0.20	–	–	0.05	0.17	0.10	0.09	–	–	–	–
Min. rotation Θ	–	–	–	–	–	–	–	–	0.14	0.22	0.15	0.17
Total Θ swept hip	–	–	–	–	0.09	0.16	–	–	–	–	–	–
Total Θ swept knee	–	–	–	–	–	–	–	–	0.08	0.17	0.07	0.20
Total Θ swept ankle	0.10	–0.04	–	–	–	–	0.04	–0.03	0.11	0.18	0.08	0.18
Total Θ swept MTP	0.14	0.28	–	–	0.08	0.20	0.07	0.11	–	–	–	–
Total Θ swept rotation	–	–	0.14	0.16	–	–	–	–	0.07	0.15	–	–
ΘV_{\max} hip	–	–	–	–	–	–	–	–	0.10	0.02	–	–
ΘV_{\max} knee	–	–	–	–	–	–	–	–	–	–	0.07	0.15
ΘV_{\max} ankle	–	–	–	–	0.16	0.04	–	–	–	–	–	–
ΘV_{\max} MTP	0.10	0.24	0.13	0.09	0.04	0.18	–	–	–	–	–	–
ΘV_{\max} rotation	0.13	0.17	–	–	0.17	0.36	0.15	0.10	–	–	–	–

Only variables with a significant simple Pearson correlation, or 0.75 posterior probability in Bayesian model averaging, were included in the partitioning analysis. *I* is the variance explained by a predictor variable that is independent of the variance explained by other predictors (i.e. not influenced by collinearity) and is always a positive number or zero. *J* is the variance explained by collinearity between predictors. A positive *J* suggests that collinearity has inflated the simple correlation between the predictor and response, whereas a negative *J* suggests that collinearity has suppressed the simple correlation.

The square root of the sum of *I* and *J* for each variable is the absolute value of its simple Pearson correlation.

MTP, metatarsophalangeal; Θ , angle; ΘV_{\max} , maximum instantaneous angular velocity.

We apologise to authors and readers for any inconvenience this error may have caused.